Role: Project Associate at EE, Indian Institute of Science

Project: Robust formation control for multiple ground robots

Responsibilities:

- 1. Read and understand the literature on formation control for multiple vehicles in the presence of disturbances.
- 2. Develop control and guidance strategies.
- 3. Implement the algorithms on the Gazebo.
- 4. Conduct experiments on ground robots and contribute to publications.

Qualifications: BE\BTech or ME\MTech in EE, ECE, Mechanical or related areas.

Requirements:

- 1. Good knowledge of controls and applied math.
- 2. Familiarity with basic MATLAB and Python.
- 3. Good experience with ROS and Gazebo would be preferable.
- 4. Communication, enthusiasm, problem-solving, and punctuality take precedence over the above-mentioned tools/frameworks.

Job Location: IISc, Bangalore.

Salary: As per IISc norms

Duration: Initially 3 months, extendable on satisfactory performance

Note: This Job post is only for M.Tech/B.Tech graduates from relevant branches as mentioned in the qualifications section and NOT FOR CURRENT STUDENTS.

Interested candidates, please email your resume to Kiran Kumari (kirank@iisc.ac.in) with the subject line "Application for project associate".

Deadline for application: Open until filled